

Refining AI-based Approximations with hybrid CP solvers

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(Courtesy to Olivier Ponsini, Claude Michel)

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Turunç

Problem: Programs with floating-point computations

Context

Problems with floating-point numbers

Objective & Approach

Example

Abstract interpretation, Fluctuat

Static analyzer

Zonotopes

Improving approximations with CP

Approach

Details

Experiments

Programs

Results over the reals

Results over floating point numbers

Conclusion

Problem

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

Problem: Programs with floating-point computations

- ▶ **Embedded Systems** (transportation, nuclear energy, medicine, avionics...) rely more and more on floating-point computations
- ▶ **C language** is most used for such applications
- ▶ The implementation of floating-point arithmetic generally conforms to **IEEE 754 standard**

Problem

Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

- ▶ **Floats** → **additional possible source of errors**
- ▶ **Counter intuitive Properties** and “pitfalls” of Floating-point arithmetic:
 - ▶ Arithmetic operators are neither associative nor distributive
 - ▶ Reasoning with **rounding**, absorption, cancellation

Examples (in simple precision)

- ▶ Absorption : $10^7 + 0.5 = 10^7$
- ▶ Cancellation : $((1 - 10^{-7}) - 1) * 10^7 = -1.192... (\neq 1)$
- ▶ $(10000001 - 10^7) + 0.5 \neq 10000001 - (10^7 + 0.5)$
- ▶ $0.1 = (0.000110011001100...)$

Semantics of real numbers versus semantics of floating-point numbers

Programs are run on the floats but:

- ▶ **Specification**, **properties** of programs
 ~> **Reasoning with real numbers**
- ▶ **Programs** are sometimes written with the semantics of real numbers “in mind”
- ▶ **Differences** between real numbers and floats
 → reveal **problems with floats**

Abstract Interpretation

→ **Approximations** over **floats** and over the **real numbers**

Problem

Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

- ▶ **Goal:** Refine the approximations computed by abstract interpretation for domains of the program variables
- ▶ **Method:** Use local consistencies to “shave” the domains

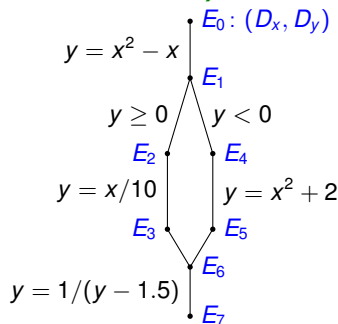
Abstract Interpretation, example

Abstract Interpretation requires:

1. **Semantics** to calculate the states of the program at various checkpoints
2. An **abstraction** to represent the states of the program
3. **Computation of a fixed point** of the equations of the semantics

Example (abstract domain of intervals)

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float x = [0,10];  
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

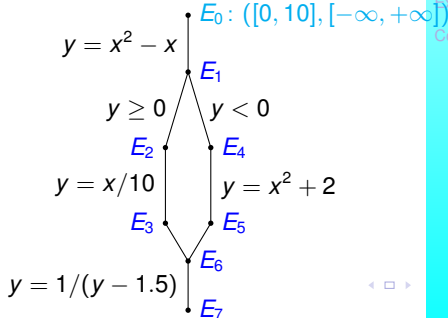
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

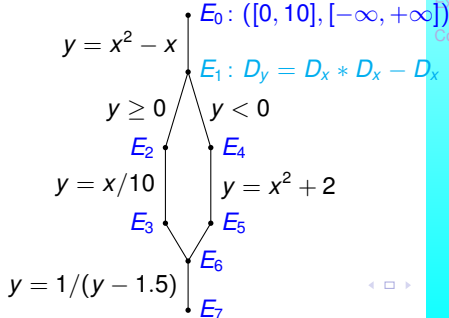
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floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

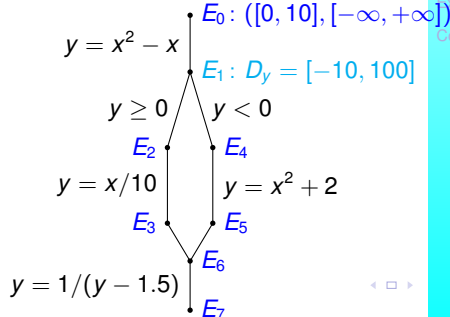
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Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

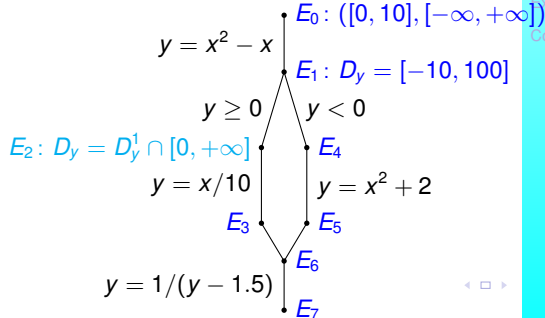
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Problems with
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Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

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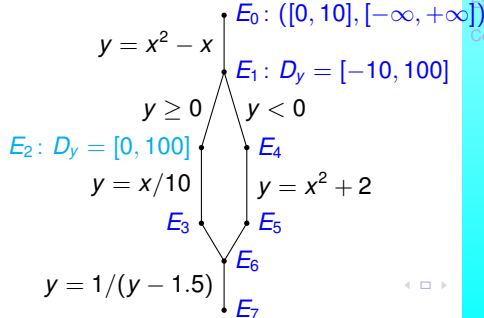
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Objective & Approach

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Experiments

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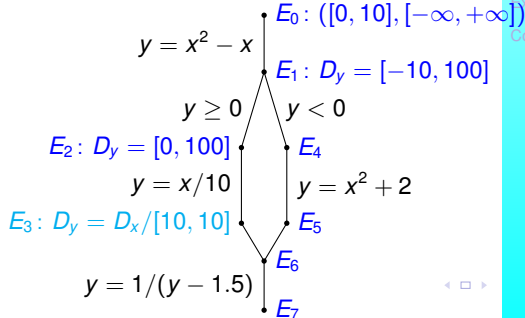
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Objective & Approach

Example

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Improving
approximations

Experiments

Conclusion

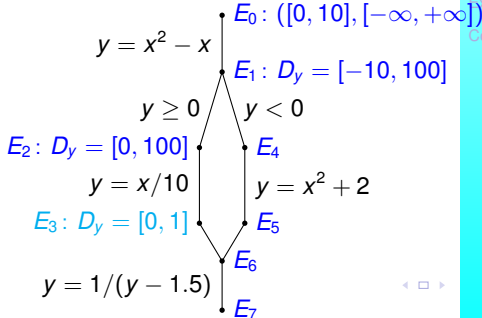
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

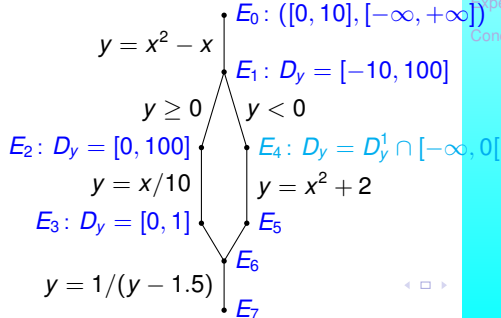
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Problem

Context

Problems with
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Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

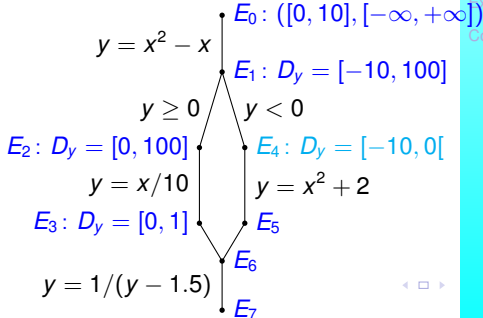
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

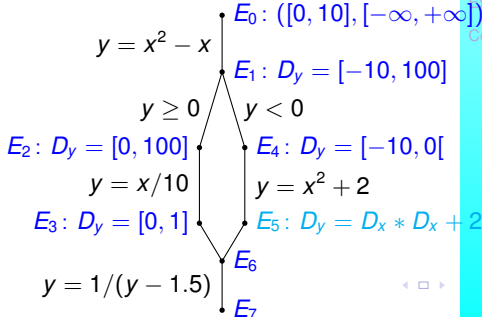
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

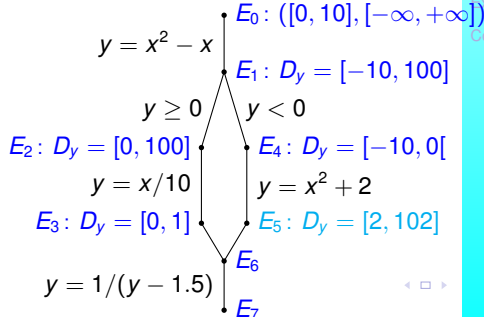
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

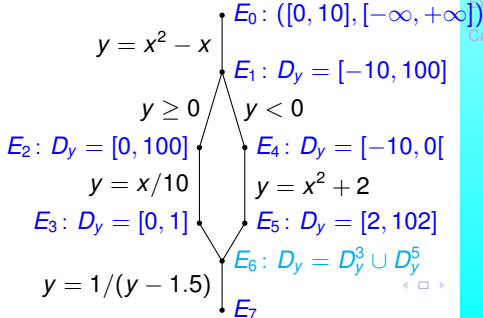
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Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

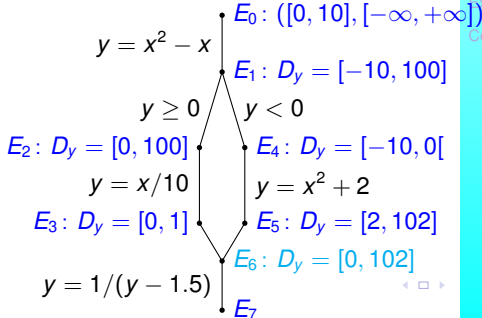
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Problem

Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

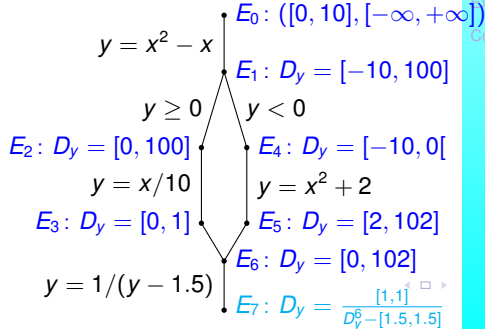
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Problem

Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

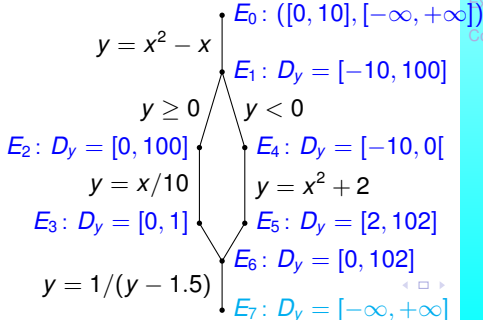
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Problem

Context

Problems with
floating-point numbers

Objective & Approach

Example

IA, Fluctuat

Improving
approximations

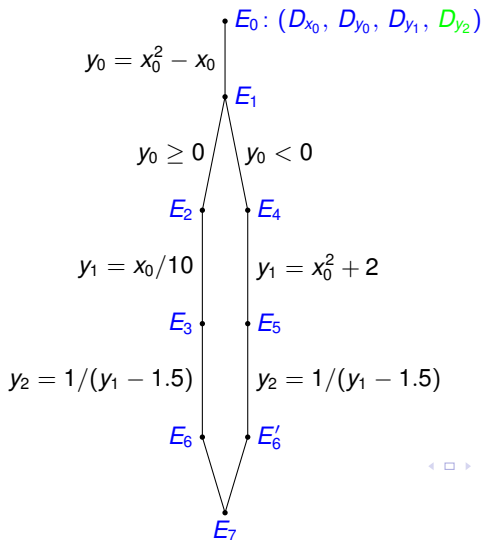
Experiments

Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving approximations

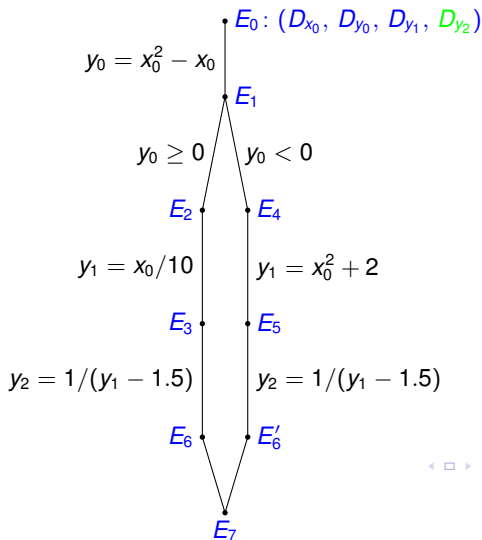
Experiments

Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving approximations

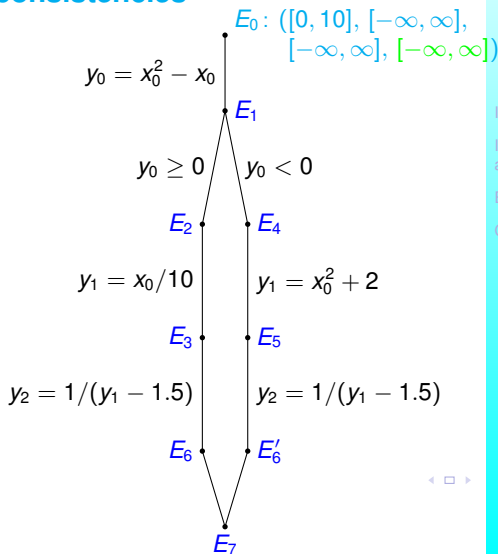
Experiments

Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving
approximations

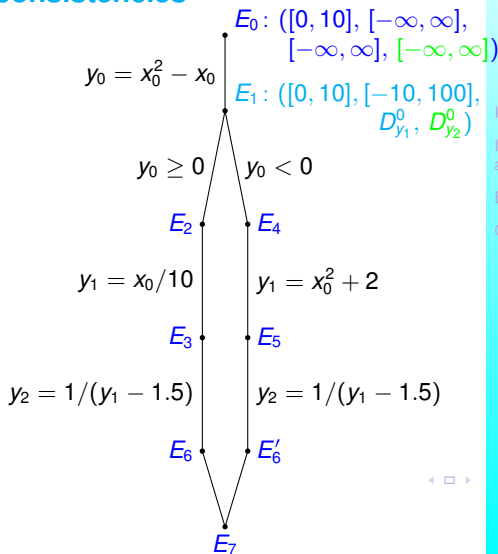
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Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving approximations

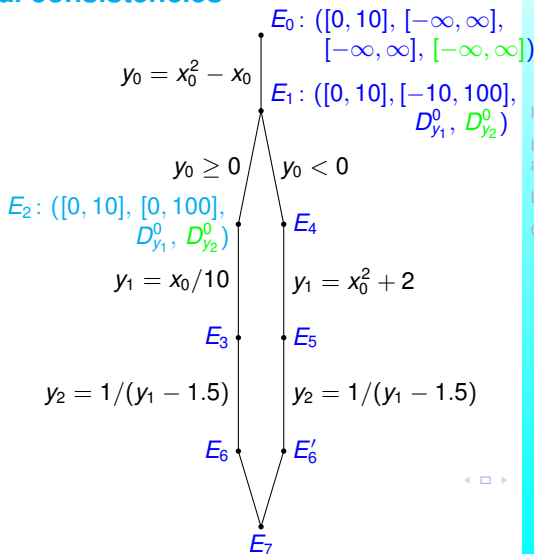
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Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving
approximations

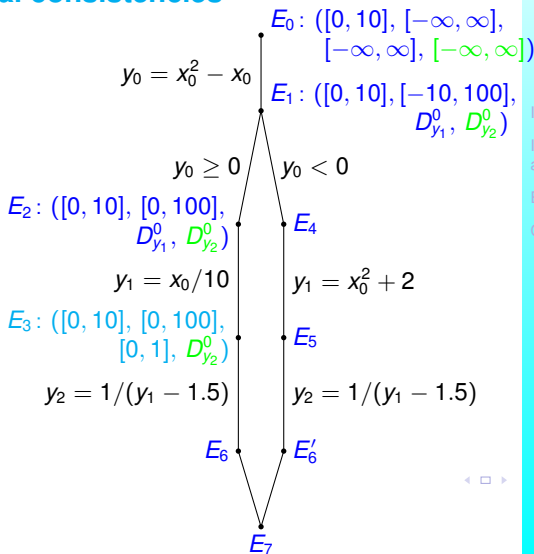
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Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving
approximations

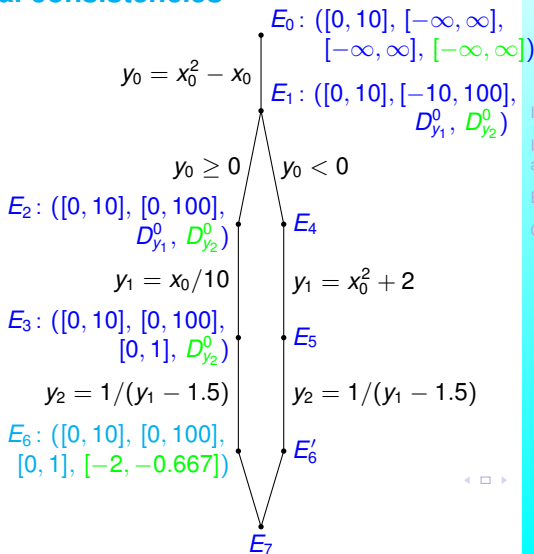
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Conclusion

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Problem

Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

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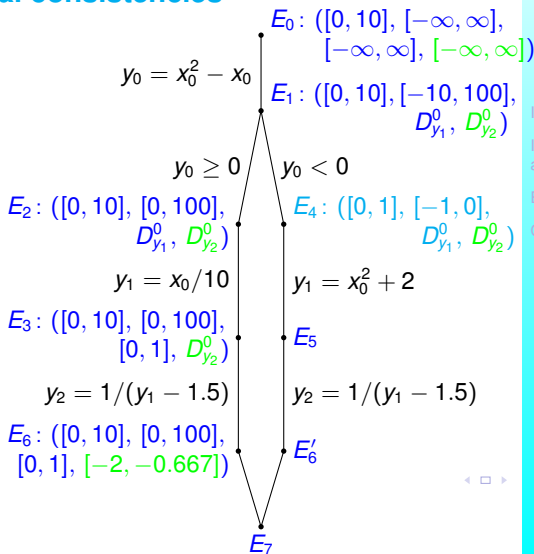
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Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

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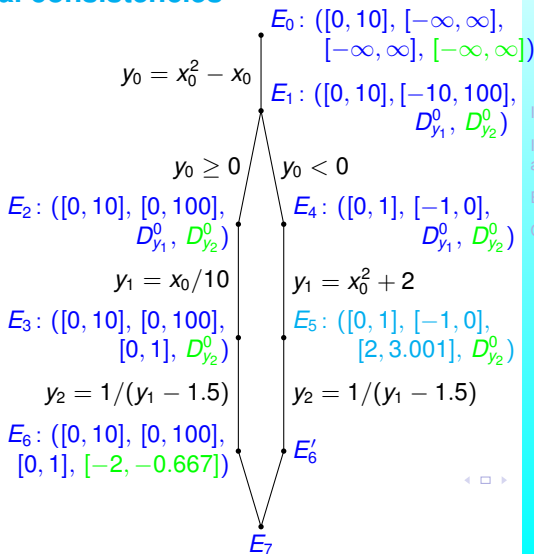
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Objective & Approach
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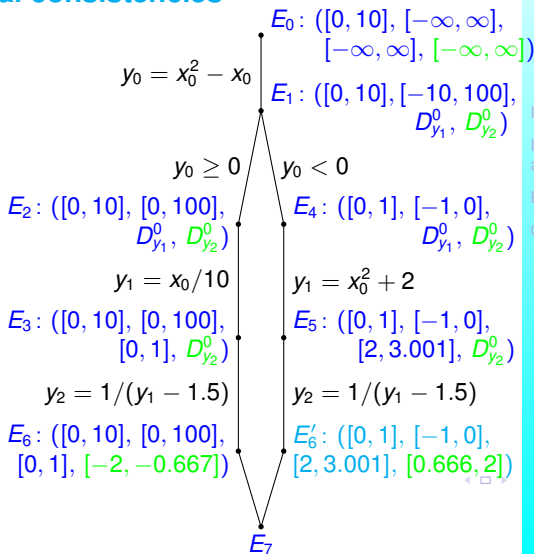
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Problems with
floating-point numbers
Objective & Approach
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IA, Fluctuat

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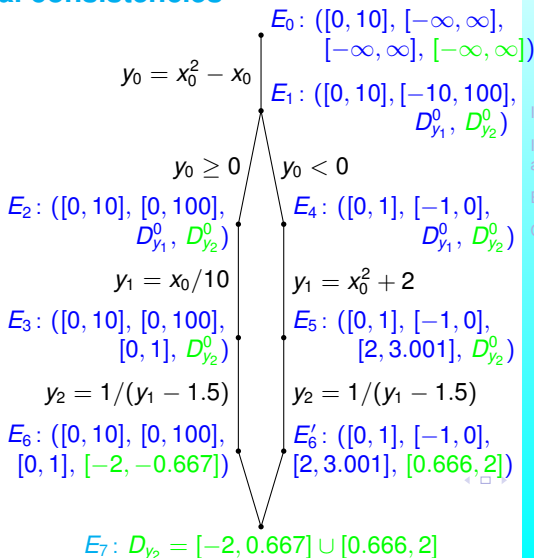
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Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

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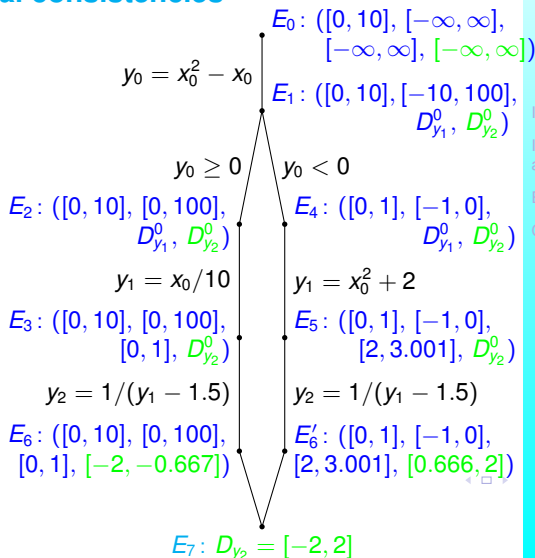
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Context
Problems with
floating-point numbers
Objective & Approach
Example

IA, Fluctuat

Improving
approximations

Experiments

Conclusion

Static analyzer for C programs based on Abstract Interpretation

→ estimating rounding errors and their propagation

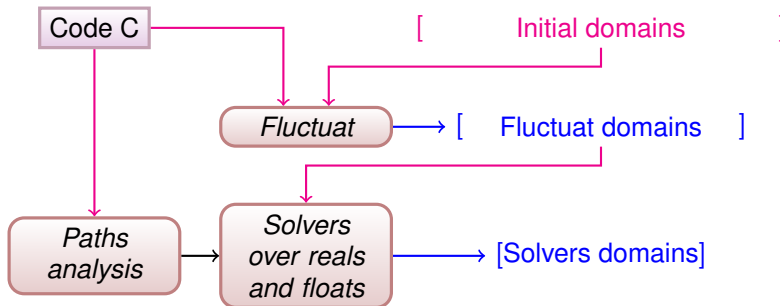
- ▶ **Programs are considered both:**
 - ▶ As a **specification** over the real numbers
 - ▶ As an **implementation** over the floats
- ▶ **Fluctuat computes for each program variable:**
 - ▶ An **over-approximation** of the domain-bounds of the variable considered as a **real number**
 - ▶ An **over-approximation** of the domain-bounds of the variable considered as a **floating-point number**
 - ▶ An **over-approximation** of the **error** associated with the variable (difference between floating-point and real number domains)
 - ▶ The **contribution of each instruction** to the error

- ▶ **Intuition** : **convex polytopes** with a **central symmetry**
 - sets of **affine forms** $x = x_0 + x_1\varepsilon_1 + \dots + x_n\varepsilon_n$ with $\varepsilon_i \in [-1, 1]$
- ▶ **Advantages**:
 - ▶ **Linear correlations** between variables are preserved
 - ▶ Nonlinear operations are over-approximated by introducing an error term
 - ▶ **Good trade-off** between performance and precision
- ▶ **Limits**:
 - ▶ Better than the intervals, worse than polyhedra
 - ▶ Not very accurate for nonlinear terms
 - ▶ Not accurate on very common program constructions as **if**

Proposed approach

Overview

We use partial consistencies to reduce the domains of variables calculated by Fluctuat



Problem

IA, Fluctuat

Improving
approximations

Approach

Details

Experiments

Conclusion

- ▶ **Set of CSP** generated for a C program:
 - ▶ A CSP is built “**on the fly**” while exploring a path
Inconsistent CSP → current **path is cut off**
 - ▶ Loops are unfolded a finite number of times
- ▶ **Filtering:**
 - ▶ **Reals:** **Hull & Box consistency** – RealPaver
 - ▶ **Floats:** **3B consistency** – FPCS
- ▶ Reduced domain of a variable: **union of the intervals** generated for this variable while filtering **all successful paths** of the program

- ▶ **Programs...**
 - ▶ `quadratic`: computing the roots of a quadratic equation (GSL library) – **conditionals**
 - ▶ `sinus7`: program of the 7th-order Taylor series of function `sinus` – **nonlinearity**
 - ▶ `rump`: polynomial of Rump – **pathological cancellation phenomenon**
 - ▶ `sqrt`: square root of a number greater than 4 (Babylonian method) – **iterative program**
- ▶ **Loss of accuracy of Fluctuat when:**
 - ▶ **Union at the earliest** of program states (join operator): `quadratic, sqrt`;
 - ▶ Domains intersection due to **conditional instructions** (meet operator): `quadratic, sqrt`;
 - ▶ Interpolation by expansion of approximations in presence of loops (widening operator): `sqrt`;
 - ▶ Approximation of **nonlinear expressions**:
`quadratic, sinus7, rump, sqrt`.

Results over the reals

	Fluctuat		RealPaver	
	Domain	Time	Domain	Time
quadratic ₁ x_0	$[-\infty, \infty]$	0.1 s	$[-\infty, 0]$	1.5 s
quadratic ₁ x_1	$[-\infty, \infty]$	0.1 s	$[-8.011, \infty]$	1.5 s
quadratic ₂ x_0	$[-2e6, 0]$	0.1 s	$[-1e6, 0]$	0.5 s
quadratic ₂ x_1	$[-1e6, 0]$	0.1 s	$[-5.186e5, 0]$	0.5 s
sinus7	$[-1.009, 1.009]$	0.1 s	$[-0.842, 0.843]$	0.3 s
rump	$[-1e37, 2e37]$	0.1 s	$[-1e36, 1.7e37]$	1.2 s
sqrt ₁	$[2.116, 2.354]$	0.1 s	$[2.121, 2.346]$	0.3 s
sqrt ₂	$[2.098, 3.435]$	0.1 s	$[2.232, 3.165]$	0.5 s

Correct solver over floating-point numbers based on 2B-consistency

→ preserves all the solutions

► **Projection functions for floats:**

- **Direct projection:** straightforward adaptation of interval arithmetic
- **Inverse projection:** using a larger format than the system variables

► **Handling of rounding modes, nonlinear expressions** and the usual mathematical functions (trigonometric. . .)

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Results over floating
point numbers

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Results over the floats

	Fluctuat		FPCS	
	Domain	Time	Domain	Time
quadratic ₁ x_0	$[-\infty, \infty]$	0.1 s	$[-\infty, 0]$	0.3 s
quadratic ₁ x_1	$[-\infty, \infty]$	0.1 s	$[-8.064, \infty]$	0.3 s
quadratic ₂ x_0	$[-2e6, 0]$	0.1 s	$[-2e6, 0]$	0.3 s
quadratic ₂ x_1	$[-1e6, 0]$	0.1 s	$[-2503.8, 0]$	0.3 s
sinus7	$[-1.009, 1.009]$	0.1 s	$[-0.853, 0.852]$	0.2 s
rump	$[-1e37, 2e37]$	0.1 s	$[-1e37, 2e37]$	0.2 s
sqrt ₁	$[2.116, 2.354]$	0.1 s	$[2.120, 2.347]$	1 s
sqrt ₂	$[-\infty, \infty]$	0.1 s	$[2.232, 3.168]$	1.6 s

► CP

► Advantages:

- Good **refutation** capabilities
- Handling nonlinear constraints

► Limits: Distinct exploration of each executable path is a **critical issue**

► AI

► Advantages:

- Good **scaling** capabilities
- Zonotopes are better approximations of linear constraints than boxes

► Limits: **Over-approximations** can be very rough

→ **Complementary** techniques

... **The hybrid approach is the best :)**